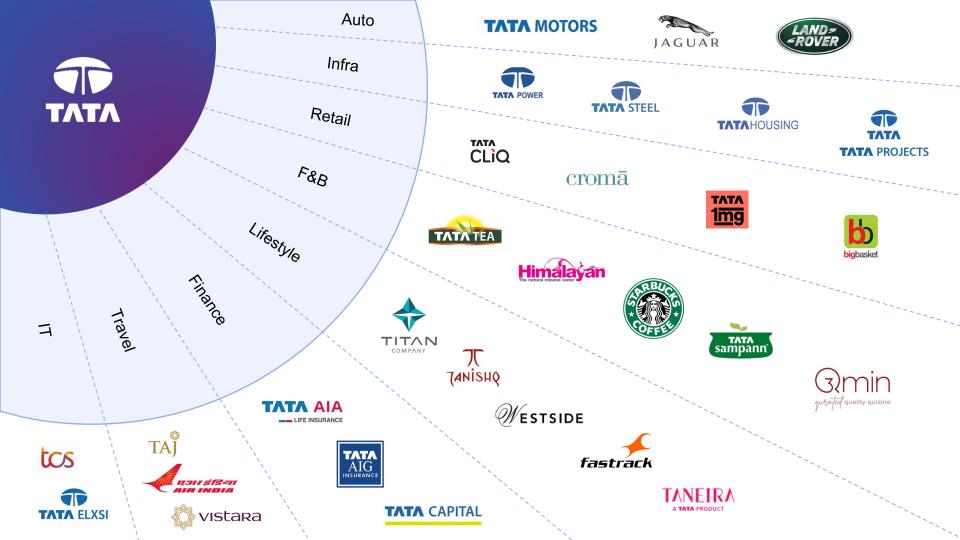




# India's Only Value-based Corporation – a Visionary, a Pioneer, a Leader, since 1868





# TATA ELXSI BUSINESS OVERVIEW



## CORE SERVICES

Engineering

Dieital



Philadelphia, USA

London, UK 🟦

Barcelona, Spain

# Transportation

#### RAIL

- Smart Mobility
- Rolling Stock and Systems
- Wayside & Signalling

#### **AUTOMOTIVE | OFF HIGHWAY**

- Passenger Experience •
- Connected & ٠ Autonomous
- Shared & Electric



# Media & Communication

#### **BROADCAST & MEDIA**

- OTT Streaming
- RDK, Android TV, CPE
- QoE, QoS, Customer Experience

1989

#### COMMUNICATIONS

- 5G. SDWAN
- Network Transformation
- Digital Transformation







# Healthcare

#### **MEDICAL DEVICES**

Europe

Paris, Netherlands, Frankfurt

Munich, Germany

- Product Design
- Systems Engineering
- Regulatory Compliance

#### PHARMACEUTICAL

- S <sub>Safety</sub>
- Packaging & Labelling
- Pharmacovigilance







Global Engineering Centres Q Sales Offices Q Headquarters

APAC

Hangzhou, Shanghai

Om Kawasaki, Japan

**Established** 

North America

Santa Clara, Toronto

Atlanta. Irvine.

Troy, USA

# **Global Presence**

Headquartered in **Bengaluru** with offices around the globe including NA, EUROPE & APAC

# NORTH AMERICA

Atlanta, Canada, Irvine, Naperville, Philadelphia, Santa Clara, Troy, Toronto

# EMEA

Dubai, France, Germany, Ireland, London Digital Studio, Netherlands, Poland, Portugal, South Africa, Spain, UK

# APAC

Japan, Malaysia

# INDIA

Bengaluru (HQ), Chennai, Hyderabad, Mumbai, Pune, Trivandrum



# Our Focus In Rail industry



Asset inspection and operations – Safe and Efficient Operations



Object detection, Perception systems (Autonomous Systems)



Safety Systems Development (Full Ownership)



Crunching the Vehicle product development cycle – Quick time to market (Competitive Advantage)



Seamless passenger experience, Passenger security & Surveillance (Smart Mobility)



IoT/Cloud for asset management and preventive maintenance (Rolling stock & wayside)



# Inspection scope areas in Railroad operations

Image: Window Stress         Image: Wi	Rolling stock	Visit       Visit         Vi	Way-side
Geometrical	Geometrical	Structural	Structural
<ul><li>Curvature</li><li>Gaps in assemblies</li><li>Measurements</li></ul>	<ul><li>Couplers</li><li>Structural deformation</li></ul>	Signage Health	<ul><li>Signage Health</li><li>Overhead Vegetation</li></ul>
Structural <ul> <li>Missing, loose parts</li> </ul>	Structural <ul> <li>Door/lid status</li> <li>Container contents</li> </ul>	Surveillance <ul> <li>Theft</li> <li>Cleanliness, spillage</li> </ul>	Civil Structures <ul> <li>Bridges</li> <li>Tunnel</li> </ul>
Damages <ul> <li>Rail end batter</li> </ul>	Container contents	Cleanliness, spillage	Environment
<ul> <li>Rall end batter</li> <li>Cracks on rail</li> <li>Broken, damaged crosstie</li> </ul>	Identification <ul> <li>Engine/ wagon ID</li> </ul>		<ul><li>Landslide</li><li>Object on track</li></ul>



# Significance of Track Inspection



- Safety
- Maintenance Planning
- Legal and Regulatory Compliance



- Asset management
- Performance monitoring

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Continuous Improvement



- Early Detection of Issues
- Operational efficiency
- Risk mitigation

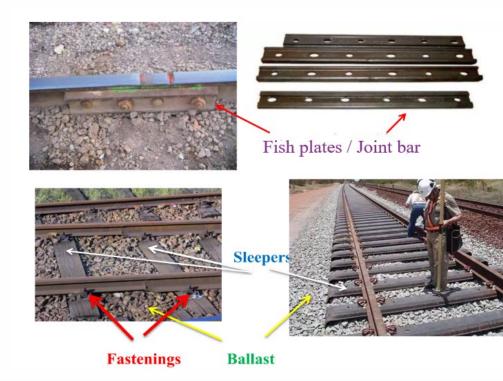


- Customer satisfaction
- Enhanced Reliability
- Financial impact
- Reputation and Public Perception





# **Rail Track Elements**







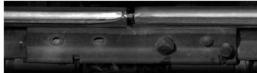
# Rail Joint Bar

Joint bars are an essential component of rail infrastructure used to connect two distinct rail tracks without the need for welding.

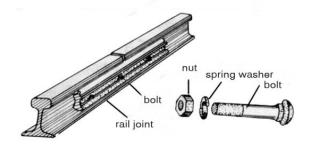




Holes



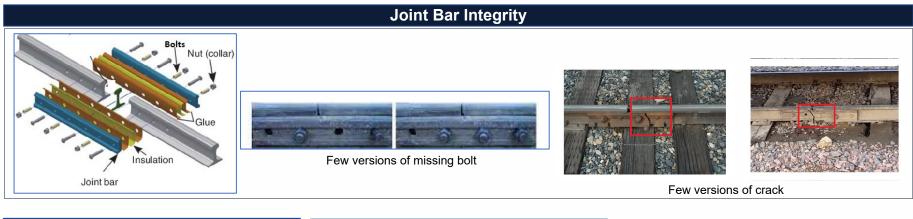
Joint Bar with two Missing Bolts Captured by the System







# **Defects in joint Bars**







# **Conventional Approaches**

## Manual Inspection







# Shortcomings of Manual Inspection

- Human Error
- Disruptions to the smooth functioning of railways.
- Time-consuming and Labor-intensive
- Limited geographic coverage

## **Shortcomings of Inspection Vehicles**

- High Capital Cost
- Limited Accessibility
- Operator Dependency

# Significance of Image-Based Solutions

- Research gap in image-based solutions
- Lack of literature work on defect detection, gap measurement from camera images

### **Inspection Vehicles**





#### Joint Bar inspection



#### Track gage Inspection



# Inspection with Drone Technology



Reliability in processing the experimental field data and defects



Localization of defect in a particular area using latitude and longitude



GUI based approach for method and results



High-quality images that contain large information for monitoring and analysis





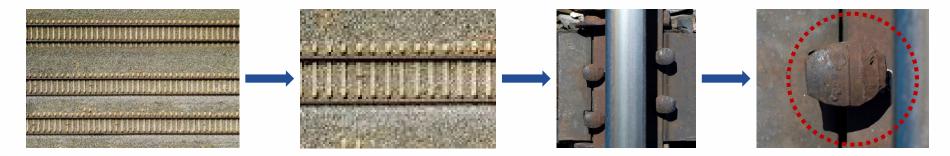


# Inspection Solution is Executed in Edge Computer

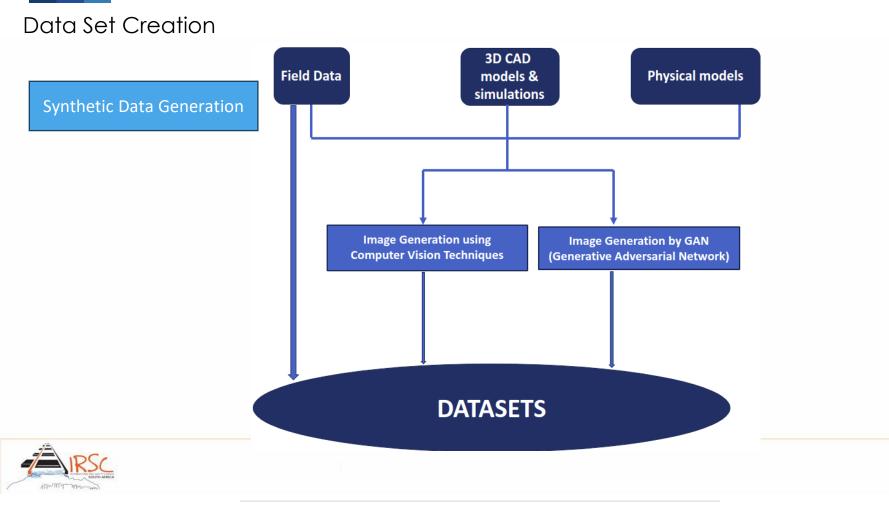


Cascaded Approach: Step-by-step detection of target component to eliminate errors

Hybrid of Computer Vision & AI/ML algorithms to achieve high accuracies







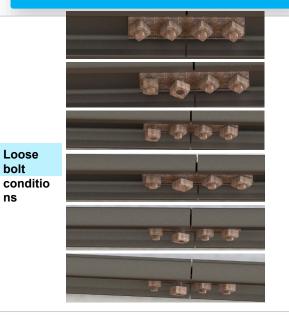
# Development Approach – Synthetic Data Generation **Best Practices/ Innovations**

#### Synthetic Data Generation tool - Able to generate millions of training data from limited parent set

#### Customized Generative Al models

# Source **Missing bolt** Image conditions

### Automated 3D Model Generation

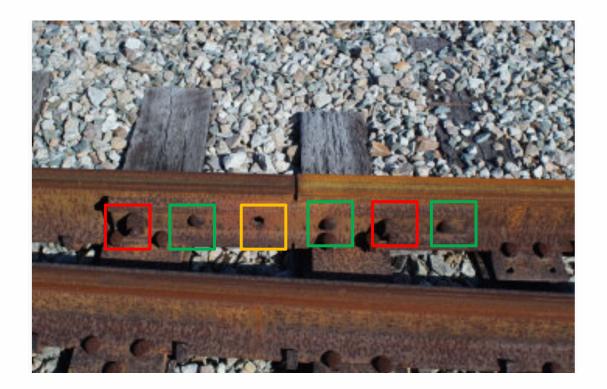


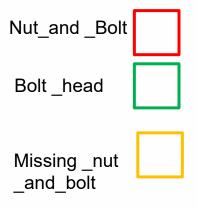
bolt

ns



Multi-Component Detection







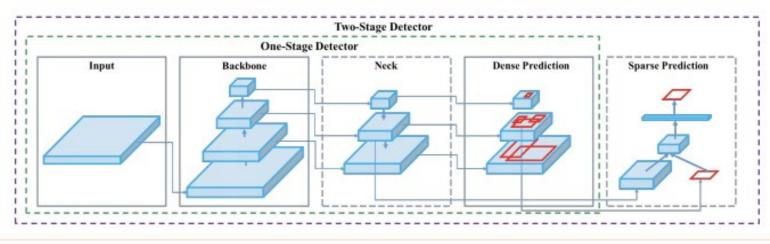


# Multi-Component Detection-YOLO V5

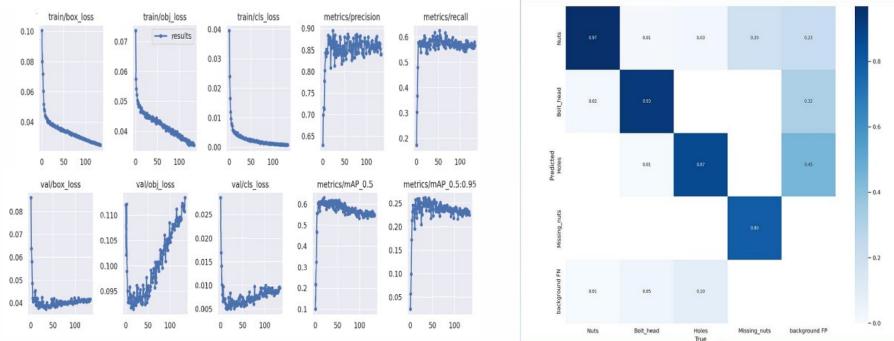
The YOLO network consists of three main pieces.

Backbone: A convolutional neural network that aggregates and forms image features at different granularities.
 Neck: A series of layers to mix and combine image features to pass them forward to prediction.

**3.**Head: Consumes features from the neck and takes box and class prediction steps.







# **Experimental Results and Inferences**

The training procedure took an average of 10 seconds for 86 batches during one epoch, and the evaluation process took an average of 9 seconds for 22 batches. Total execution time was 0.435 hours i.e. 26.1 minute for 100 epochs.



# **Experimental Results and Inferences**

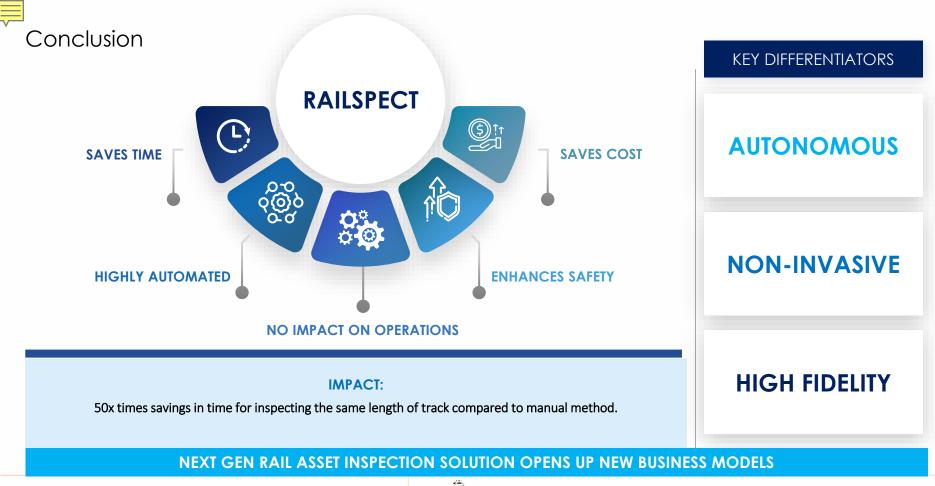
Hyper parameters	Values used	Model	Training Res	ults
	for training		-Prediction (9	%)
Learning Rate [lr-Final one cycle LR]	0.0001	Yolo5s.pt	Nut	- 97
Momentum	0.984		Bolt head	- 93
Classification Loss gain	0.5		Holes	- 87
Object loss gain	1.0		Missing Nut	- 80
Learning Rate [lrf -Final one cycle LR]	0.001	Yolo5s.pt	Nut	- 96
Momentum	0.937		Bolt head	- 89
			Holes	- 82
			Missing Nut	- 80
Learning Rate [lr]	0.01	Yolo5s.pt	Nut	- 98
Learning Rate [lrf -Final one cycle LR]	0.01		Bolt head	- 83
Classification Loss gain	0.3		Holes	- 89
Object loss gain	0.7		Missing Nut	- null

Class name	Precision value	Recall value	Accuracy (%)
Nut	82.9	98.9	97.0
Bolt_head	80.1	948	94.6
Holes	73.1	89.6	87.6
Missing nut	0.64	98.7	80.0

Hyper parameter tuning constructed based on the learning rate and momentum and further optimized using the Adaptive Moment Estimation (ADAM) optimizer











# Thank You

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#### RAIL SAFETY ON THE RIGHT TRACK