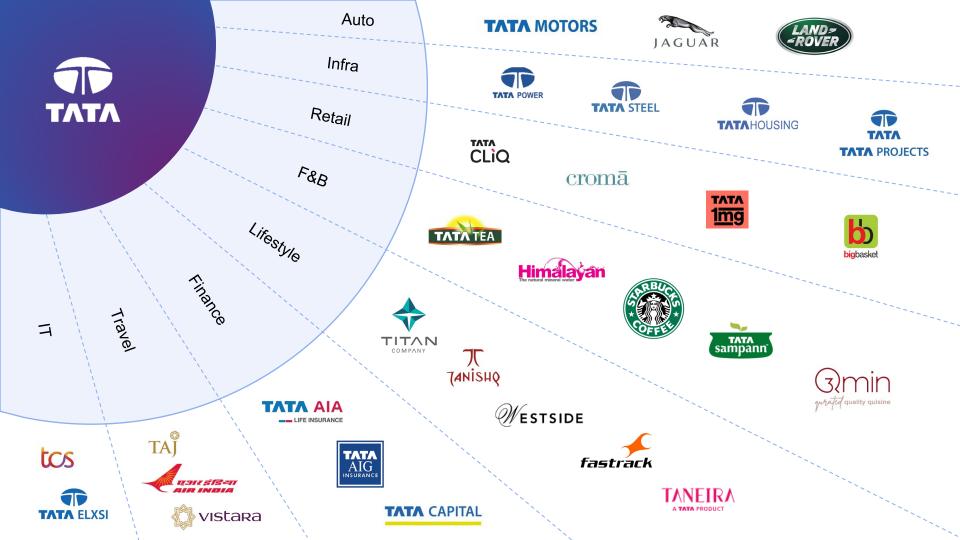




India's Only Value-based Corporation – a Visionary, a Pioneer, a Leader, since 1868





TATA ELXSI BUSINESS OVERVIEW



CORE SERVICES

Engineering

Dieital



Philadelphia, USA

London, UK 🟦

Barcelona, Spain

Transportation

RAIL

- Smart Mobility
- Rolling Stock and Systems
- Wayside & Signalling

AUTOMOTIVE | OFF HIGHWAY

- Passenger Experience •
- Connected & ٠ Autonomous
- Shared & Electric



Media & Communication

BROADCAST & MEDIA

- OTT Streaming
- RDK, Android TV, CPE
- QoE, QoS, Customer Experience

1989

COMMUNICATIONS

- 5G. SDWAN
- Network Transformation
- Digital Transformation







Healthcare

MEDICAL DEVICES

Europe

Paris, Netherlands, Frankfurt

Munich, Germany

- Product Design
- Systems Engineering
- Regulatory Compliance

PHARMACEUTICAL

- S _{Safety}
- Packaging & Labelling
- Pharmacovigilance







Global Engineering Centres Q Sales Offices Q Headquarters

APAC

Hangzhou, Shanghai

Om Kawasaki, Japan

Established

North America

Santa Clara, Toronto

Atlanta. Irvine.

Troy, USA

Global Presence

Headquartered in **Bengaluru** with offices around the globe including NA, EUROPE & APAC

NORTH AMERICA

Atlanta, Canada, Irvine, Naperville, Philadelphia, Santa Clara, Troy, Toronto

EMEA

Dubai, France, Germany, Ireland, London Digital Studio, Netherlands, Poland, Portugal, South Africa, Spain, UK

APAC

Japan, Malaysia

INDIA

Bengaluru (HQ), Chennai, Hyderabad, Mumbai, Pune, Trivandrum



Our Focus In Rail industry



Asset inspection and operations – Safe and Efficient Operations



Object detection, Perception systems (Autonomous Systems)



Safety Systems Development (Full Ownership)



Crunching the Vehicle product development cycle – Quick time to market (Competitive Advantage)



Seamless passenger experience, Passenger security & Surveillance (Smart Mobility)



IoT/Cloud for asset management and preventive maintenance (Rolling stock & wayside)



Inspection scope areas in Railroad operations

Image: Window Stress Image: Wi	Rolling stock	Visit Visit Vi	Way-side
Geometrical	Geometrical	Structural	Structural
CurvatureGaps in assembliesMeasurements	CouplersStructural deformation	Signage Health	Signage HealthOverhead Vegetation
Structural Missing, loose parts 	Structural Door/lid status Container contents 	Surveillance Theft Cleanliness, spillage 	Civil Structures Bridges Tunnel
Damages Rail end batter 	Container contents	Cleanliness, spillage	Environment
 Rall end batter Cracks on rail Broken, damaged crosstie 	Identification Engine/ wagon ID 		LandslideObject on track



Significance of Track Inspection



- Safety
- Maintenance Planning
- Legal and Regulatory Compliance



- Asset management
- Performance monitoring

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Continuous Improvement



- Early Detection of Issues
- Operational efficiency
- Risk mitigation

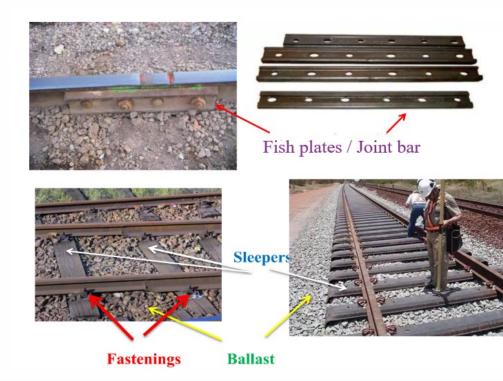


- Customer satisfaction
- Enhanced Reliability
- Financial impact
- Reputation and Public Perception





Rail Track Elements







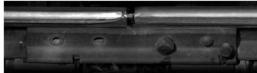
Rail Joint Bar

Joint bars are an essential component of rail infrastructure used to connect two distinct rail tracks without the need for welding.

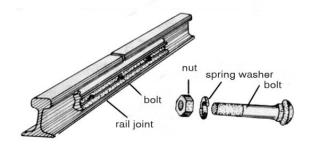




Holes



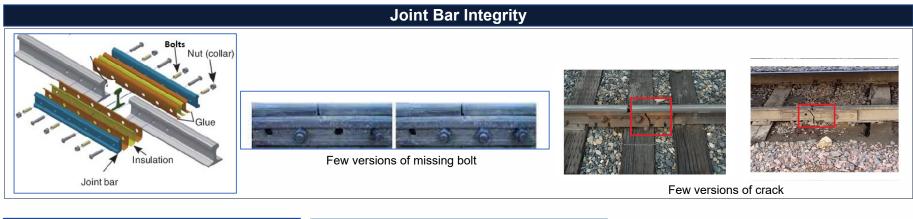
Joint Bar with two Missing Bolts Captured by the System







Defects in joint Bars







Conventional Approaches

Manual Inspection







Shortcomings of Manual Inspection

- Human Error
- Disruptions to the smooth functioning of railways.
- Time-consuming and Labor-intensive
- Limited geographic coverage

Shortcomings of Inspection Vehicles

- High Capital Cost
- Limited Accessibility
- Operator Dependency

Significance of Image-Based Solutions

- Research gap in image-based solutions
- Lack of literature work on defect detection, gap measurement from camera images

Inspection Vehicles





Joint Bar inspection



Track gage Inspection



Inspection with Drone Technology



Reliability in processing the experimental field data and defects



Localization of defect in a particular area using latitude and longitude



GUI based approach for method and results



High-quality images that contain large information for monitoring and analysis





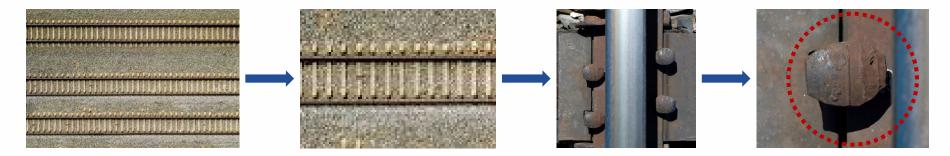


Inspection Solution is Executed in Edge Computer

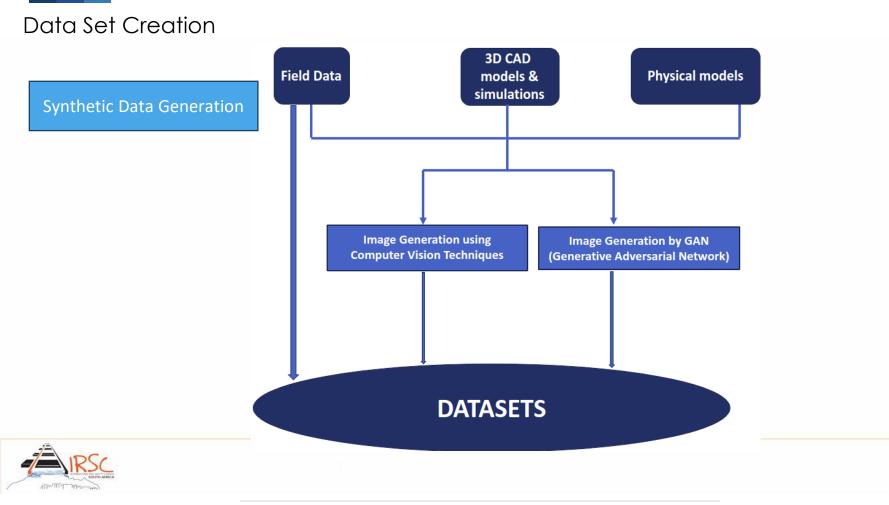


Cascaded Approach: Step-by-step detection of target component to eliminate errors

Hybrid of Computer Vision & AI/ML algorithms to achieve high accuracies







Development Approach – Synthetic Data Generation **Best Practices/ Innovations**

Synthetic Data Generation tool - Able to generate millions of training data from limited parent set

Customized Generative Al models

Source **Missing bolt** Image conditions

Automated 3D Model Generation

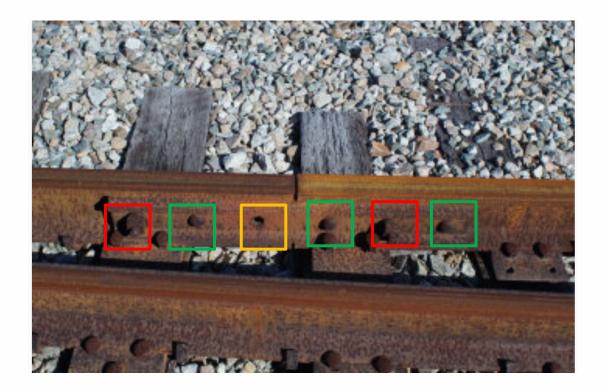


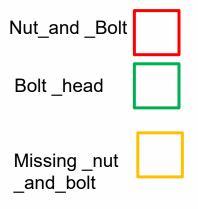
bolt

ns



Multi-Component Detection







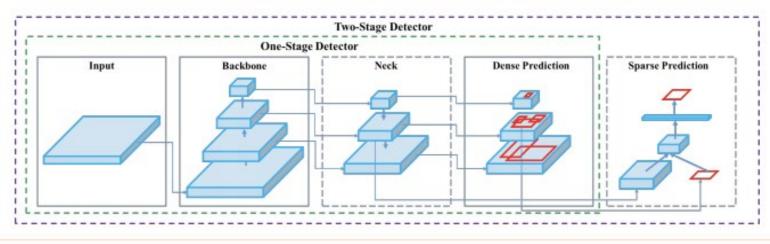


Multi-Component Detection-YOLO V5

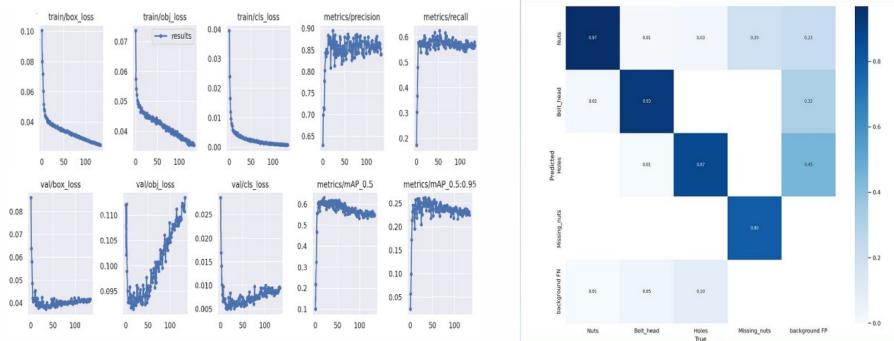
The YOLO network consists of three main pieces.

Backbone: A convolutional neural network that aggregates and forms image features at different granularities.
 Neck: A series of layers to mix and combine image features to pass them forward to prediction.

3.Head: Consumes features from the neck and takes box and class prediction steps.







Experimental Results and Inferences

The training procedure took an average of 10 seconds for 86 batches during one epoch, and the evaluation process took an average of 9 seconds for 22 batches. Total execution time was 0.435 hours i.e. 26.1 minute for 100 epochs.



Experimental Results and Inferences

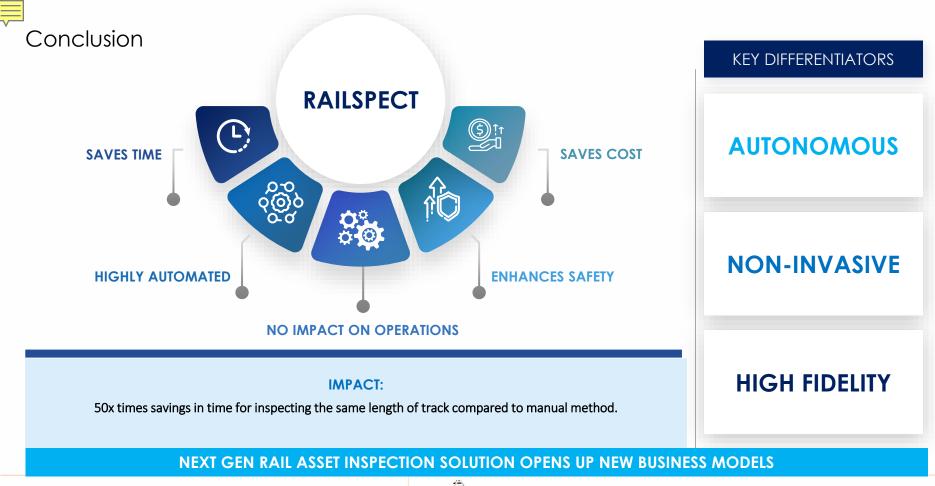
Hyper parameters	Values used	Model	Training Res	ults
	for training		-Prediction (9	%)
Learning Rate [lr-Final one cycle LR]	0.0001	Yolo5s.pt	Nut	- 97
Momentum	0.984		Bolt head	- 93
Classification Loss gain	0.5		Holes	- 87
Object loss gain	1.0		Missing Nut	- 80
Learning Rate [lrf -Final one cycle LR]	0.001	Yolo5s.pt	Nut	- 96
Momentum	0.937		Bolt head	- 89
			Holes	- 82
			Missing Nut	- 80
Learning Rate [lr]	0.01	Yolo5s.pt	Nut	- 98
Learning Rate [lrf -Final one cycle LR]	0.01		Bolt head	- 83
Classification Loss gain	0.3		Holes	- 89
Object loss gain	0.7		Missing Nut	- null

Class name	Precision value	Recall value	Accuracy (%)
Nut	82.9	98.9	97.0
Bolt_head	80.1	948	94.6
Holes	73.1	89.6	87.6
Missing nut	0.64	98.7	80.0

Hyper parameter tuning constructed based on the learning rate and momentum and further optimized using the Adaptive Moment Estimation (ADAM) optimizer











Thank You

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RAIL SAFETY ON THE RIGHT TRACK