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23

ETY COUNCIL

strial World

OCTOBER 1 - 6, 2023

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INTERNATIONAL RAILWAY SAF

"Recharging Railwaying railway"

CAPE TOWN, O

Mr. David YAM
Electrical and Mechanical Services Department

Train-borne Railway Infrastructure Inspection System

Electrical and Mechanical Services Department (EMSD)

- The **Railway Safety Regulator** which regulates safety of mass transit railways, tramways, and peak trams in Hong Kong
- The **"Innovation Facilitator"** of the Government to support and facilitate I&T application by government departments for service improvement and smart city development

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Railway Safety Regulator



"Innovation Facilitator"



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E&M Inno-Portal

E&M InnoPortal® 

EMSD launched an online technological demand matching platform in March 2018 to facilitate wider adoption of I&T.

"I&T Wishes" for resolving specific railway safety problems by I&T application



Railway Safety Regulator and railway operator

I&T Knowledge and Innovative Ideas



I&T Solution Provider
(e.g. Universities and Research Institutes)



Pilot I&T Projects in Railway Environment



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Background

Railway Network in Hong Kong

- 10 Heavy Rails
- 1 Light Rail & 1 High Speed Rail
- Long Track length
- Long Service Hours

Infrastructure Conditions Inspection

- Manual Visual Inspection
- Non-Traffic Hour (2-3 hours)
- Labour-intensive & Time-consuming



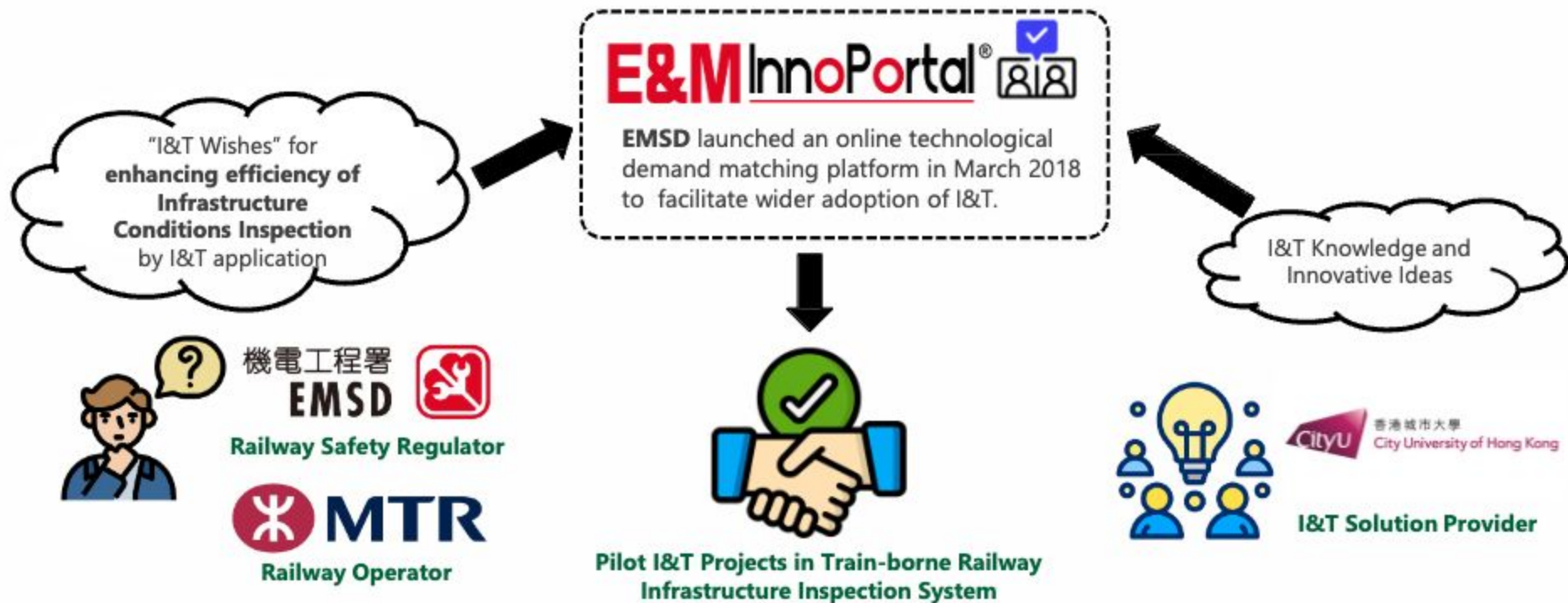
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Matching of "I&T Wishes" and "I&T Solution" in E&M Inno-Portal



Invention

The World's 1st Train-borne High Speed Scanning System



<https://youtu.be/dwkecDy72L4>

Silver Medal Award
International Exhibition of
Inventions of Geneva in 2023



Detect & Predict the railway infrastructure defects



IDS



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System Design



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Technology Adopted

1. 4th Generation LiDAR



- Enabling SLAM
- 10 Rotations (2.6 million points) per sec
- Global Shutter
- Rebuilt 3D BIM model
- Max Range: 50 Meter
- Vertical / Horizontal Field of View: 90° and 360 °



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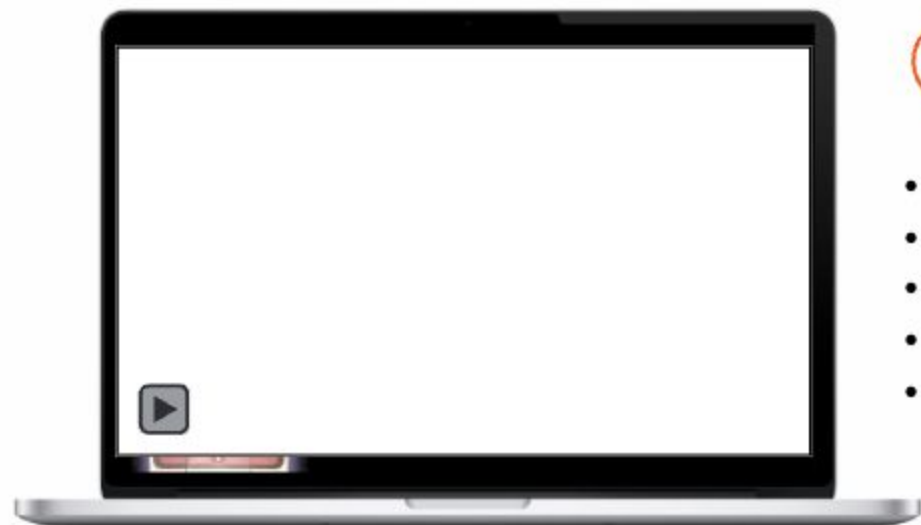


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Technology Adopted

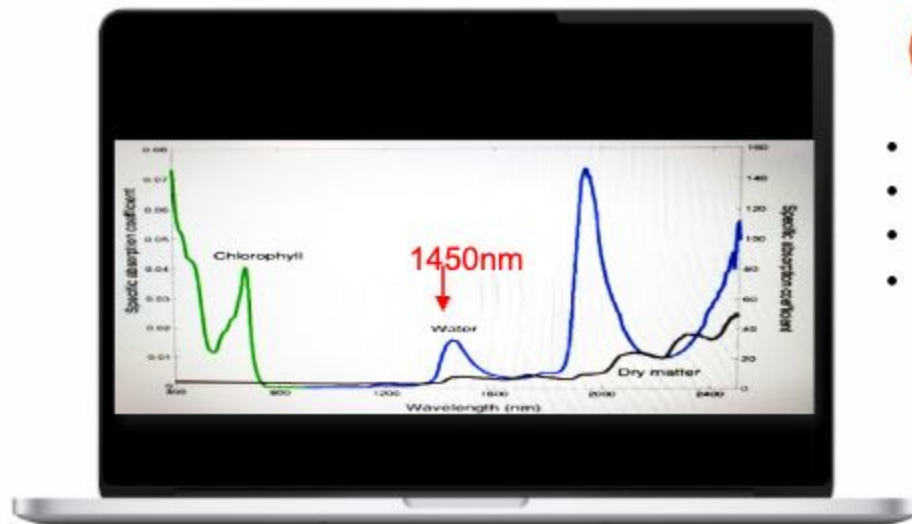
2. Stereo Computer Vision and Advanced AI Algorithms



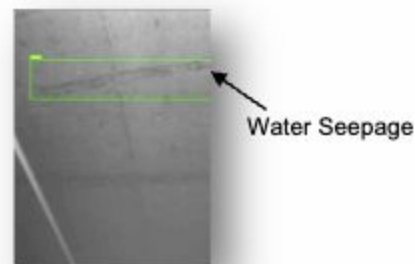
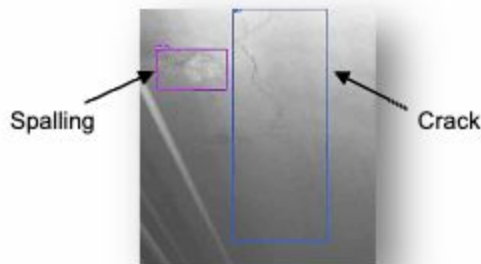
- Like a pair of human eyes
- Widen the view of scene and depth of view
- YOLOV4 and DINO-IR AI Models
- Enhanced detection accuracy
- Trend Prediction

Technology Adopted

3. Dual-band Infrared Imaging



- Non-Visible Light
- Near-infrared (850nm) & Short-wave infrared (1450nm)
- Expand the dynamic range of IR detection
- Distinguish the concrete crack and water seepage



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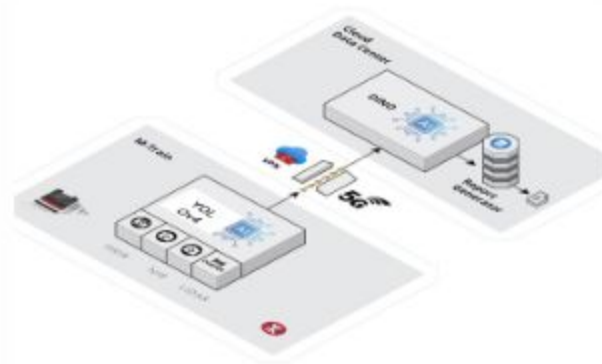


Technology Adopted

4. 5G Edge Computing



- Real-time Detection at 80 km/h train speed
- Fully Automated
- Inspection during Service Hours



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AI and Analytics Engine

Stage 1

YOLO V4 AI
On Train



- ✓ Light Weight AI
- ✓ Preliminary screening

Stage 2

DINO-IR AI
On Cloud Server



- ✓ Powerful AI
- ✓ Detailed Identification
- ✓ Positioning

Stage 3

Report Generation
On Cloud Server



- ✓ Reporting and trending
- ✓ Date, Time, Location, Types of defect, and snapshot photo

CLEANSING

Data Cleansing & Transformation

EMBEDDING

N-Dimensional Tensor Matrix

SIMILARITY

Learning the Similarity

HYBRID DECISION TREE

Data Compensation

CONVOLUTION NEURAL NETWORK

Feature Extraction

FINAL DECISION MAKING

Identify the types of defect



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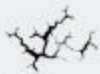
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Target Result



Concrete Spalling: 150mm(W) x 150mm (H) ($\pm 5\%$)



Concrete Crack: 10mm (W) and 150mm (H) ($\pm 5\%$)



Water Seepage: 150mm (W) x 150mm (H) ($\pm 5\%$)



Trackside Equipment Displacement: 50mm ($\pm 5\%$)



Overall Defect Detection Accuracy: 80%



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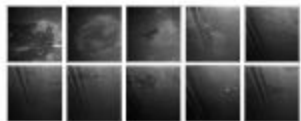


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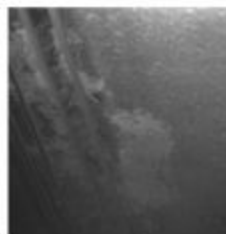
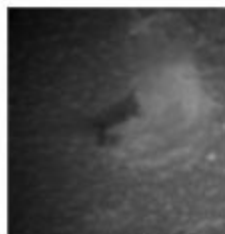
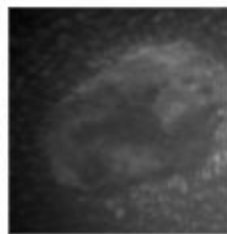


Tests and Results

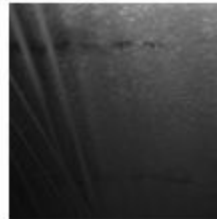
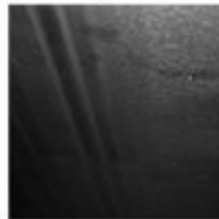
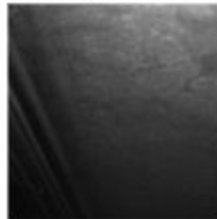
Concrete Spalling, Concrete Crack and Water Seepage



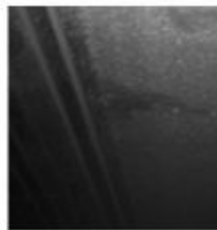
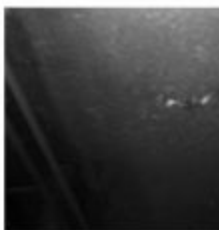
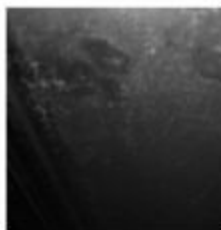
Stage 1: Results from Preliminary Screening by YOLO V4 AI Model on Passenger Train



Spalling



Crack



Water Seepage

Stage 2: Results from Detailed Identification by DINO AI Model on Cloud Server



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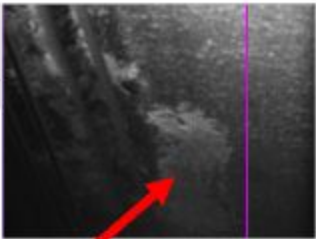
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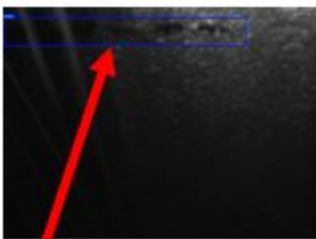
Tests and Results

Concrete Spalling, Concrete Crack and Water Seepage

Stage 3: Report Generation on Cloud Server

Date: 7 April 2023		Type of Defect Reported: Spalling Structure: WTS-LOF
Location:	WTS-LOF D/T	
Sub-Location:	KM 105.142 D/T	
Defect Type:	Spalling	
Date/Time Detected:	7 April 2023 03:04:02 a.m.	

Concrete Spalling

Date: 7 April 2023		Type of Defect Reported: Crack Structure: WTS-LOF
Location:	WTS-LOF D/T	
Sub-Location:	KM 105.163 D/T	
Defect Type:	Crack	
Date/Time Detected:	7 April 2023 03:05:21 a.m.	

Concrete Crack

Date: 7 April 2023		Type of Defect Reported: Water Seepage Structure: WTS-LOF
Location:	WTS-LOF D/T	
Sub-Location:	KM 105.074 D/T	
Defect Type:	Seepage	
Date/Time Detected:	7 April 2023 03:01:53 a.m.	

Water Seepage

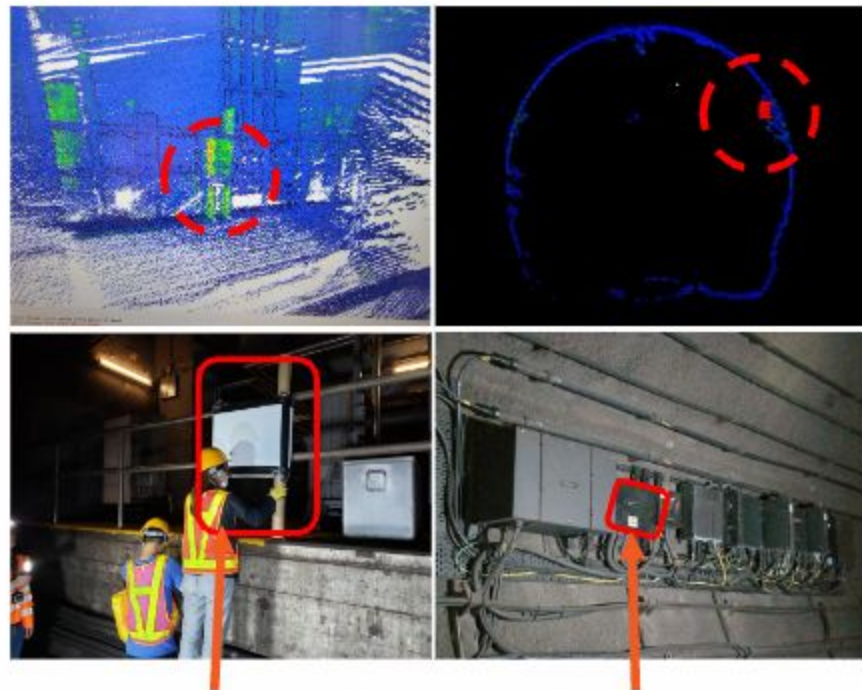
Tests and Results

Trackside Equipment Displacement

- Protection Barrier
- Tunnel Radio Amplifier
- Test Objects at High Speed Section (up to 80km/hr)



Loosen Cable Hanger



Protection Barrier Relocated Door Opened



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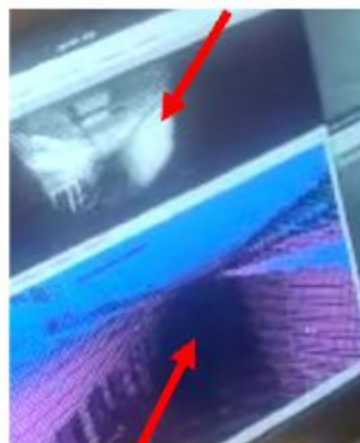


Tests and Results

Result of Defect Detection

- The system installation and testing was completed with trial run since March 2023
- Concrete Spalling: 81.7%
- Concrete Crack: 84.3%
- Water Seepage: 84.4%
- Trackside Equipment Displacement: All simulated scenarios detected in the testing
- Positioning of Defect Location: Accuracy range within 7m after using fixed point marker to specified position (i.e. platform head wall) along with point cloud

Thermal Image



3D Point Cloud

Further Enhancement

1. Enhancement of Detection Accuracy
 - Getting more data for machine learning of AI Model
2. Positioning of Defect Locations
 - Using more fixed point markers to specified positions with unique features along with point cloud



Conclusion

Train-borne Railway Infrastructure Inspection System

- Enhance efficiency of infrastructure conditions inspection by using artificial intelligence
- Facilitate trend analysis on detection and prediction of the railway infrastructure defects
- Better to utilize the maintenance window for other works





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